

On the Capacity of Block Fading Optical Wireless Channels

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Abstract—This paper investigates the capacity of block fading optical intensity channels with more transmit than receive antennas under different assumptions on the transmitter’s channel state information (CSI). Lower and upper bounds on the capacities are derived using the entropy power inequality (EPI) and a dual expression for capacity. Our lower-bounds for perfect and partial CSI utilize a transmit-antenna cooperation strategy based on minimum-energy signaling, which we proposed recently. For perfect CSI, this lower bound matches the upper bound asymptotically in the high signal-to-noise-ratio (SNR) regime. For imperfect CSI, our lower bound is close to its perfect-CSI counterpart.

I. INTRODUCTION

We consider a block fading optical wireless communication system where the transmitter modulates the intensity of optical signals that are emitted by light emitting diodes (LEDs) or laser diodes (LDs), and the receiver measures incoming optical intensities by means of photodetectors. As a first approximation, the noise in such systems can be assumed to be Gaussian and independent of the transmitted signal (thermal noise, surrounding light sources). Inputs are nonnegative because they represent intensities. Moreover, they are typically subject to both peak- and average-power constraints, where the peak-power constraint is mainly due to technical limitations of the used components, whereas the average-power constraint is imposed by battery limitations and safety considerations.

Recent years have seen extensive studies of *intensity-modulation-direct-detection (IM-DD)* systems [1]–[6], where transmitters are equipped with $n_T \geq 1$ LEDs or LDs and receivers with $n_R \geq 1$ photo detectors. In the high signal-to-noise ratio (SNR) regime, [5] determined the asymptotic capacity when the channel matrix is invertible or of full column-rank. For general MIMO channels with average-power constraint only, the asymptotic high-SNR capacity was determined in [7], [8]. In the case when the channel input is subject to both peak- and average-power constraints, the achievable high-SNR pre-log (degrees of freedom) is shown in [7], [8], and recently, the exact high-SNR asymptotic capacity is characterized in [9]. Furthermore, the asymptotic capacity in the low-SNR regime is also derived in [6], [9].

In this paper, we consider a block fading IM-DD channel where there are more transmit than receive antennas:

$$n_T > n_R \geq 1. \quad (1)$$

The capacity of block fading channels heavily depends on the channel modeling (such as the models for turbulence, fading, and antenna correlation) and the availability of channel state information (CSI) at the transmitter and receiver. Inspired by the previous works [10]–[12] in the classic block fading Gaussian channels, we assume that the receiver has perfect CSI, and study three different versions of transmitter CSI: no CSI, perfect CSI, and limited CSI. The main contributions of this paper are as follows.

- Lower bounds are presented for the capacities without CSI, with perfect CSI, and with limited CSI.
- The lower bounds for perfect and limited CSI are obtained using the minimum-energy signaling strategy we have derived in [9], which sets at each instant in time a subset of $n_T - n_R$ antennas to zero or to full power, and uses only the remaining n_R antennas for signaling.
- For perfect CSI, the lower bound matches a new duality-based upper bound in the high signal-to-noise ratio (SNR) regime.
- For limited CSI, the lower bound is close to the one with perfect CSI, but requires only $(n_T - n_R) \log_2 \binom{n_T}{n_R}$ bits of feedback in each block.

II. CHANNEL MODEL

Consider the following $n_R \times n_T$ block fading channel:

$$\mathbf{Y}_t[n] = \mathbb{H}_t \mathbf{x}_t[n] + \mathbf{Z}_t[n], \quad (2)$$

where $t \in \{1, 2, \dots, B\}$ denotes the block index, with B being the number of blocks; $n \in \{1, 2, \dots, N\}$ denotes the symbol index along a block, with N being the block length; $\mathbf{x}_t[n] = (x_t^{(1)}[n], \dots, x_t^{(n_T)}[n])^\top$ denotes the n_T -dimensional channel input vector; $\mathbf{Z}_t[n]$ denotes the n_R -dimensional noise vector with independent standard Gaussian entries,

$$\mathbf{Z}_t[n] \sim \mathcal{N}(0, 1); \quad (3)$$

and

$$\mathbb{H}_t = [\mathbf{H}_t^{(1)}, \mathbf{H}_t^{(2)}, \dots, \mathbf{H}_t^{(n_T)}] \quad (4)$$

is a random $n_R \times n_T$ channel matrix with nonnegative entries. Thus, $\mathbf{H}_t^{(1)}, \dots, \mathbf{H}_t^{(n_T)}$ are n_R -dimensional random column vectors. The channel noises $\{\mathbf{Z}_t[n]\}$ are independent and identically distributed (IID) inside and across blocks. The

channel matrix \mathbb{H}_t remains constant within each block and is IID across blocks. We assume it has finite density $f(\mathbb{H}_t)$ over the set of nonnegative real numbers (e.g., Rayleigh, Weibull, Pareto, or gamma distributions).

Since the channel inputs correspond to optical intensities, they are nonnegative:

$$x_t^{(k)}[n] \in \mathbb{R}_0^+, \quad k = 1, \dots, n_T, \quad (5)$$

for all $t \in \{1, \dots, B\}$ and $n \in \{1, \dots, N\}$. Moreover, we assume that the inputs are subject to a peak-power (peak-intensity) and a *per-block* average-power (average-intensity) constraint:

$$\Pr[X_t^{(k)}[n] > A] = 0, \quad \forall k \in \{1, \dots, n_T\}, \quad (6a)$$

$$\frac{1}{N} \mathbb{E} \left[\sum_{n=1}^N \|\mathbf{X}_t[n]\|_1 \right] \leq E, \quad \forall t \in \{1, 2, \dots, B\}, \quad (6b)$$

for some fixed parameters $A, E > 0$. The ratio between the allowed average power and the allowed peak power is denoted by α :

$$\alpha \triangleq \frac{E}{A}. \quad (7)$$

Note that A describes the maximum power of each single LED, while E describes the allowed total average power of all LEDs together. Moreover, power allocation is permitted only inside each block. This restriction on power allocation is to prevent large visible fluctuation in the light.

The goal of the communication is to convey a random message $M \in \{1, 2, \dots, M\}$ from the transmitter to the receiver over a fixed number of B blocks. Encoding is described separately for each kind of CSI. Decoding is as follows. Based on its observed NB outputs $\mathbf{Y}_1[1], \dots, \mathbf{Y}_B[N]$ and its knowledge of the B channel state matrices $\mathbb{H}_1, \dots, \mathbb{H}_B$, it produces an estimate

$$\hat{M} \triangleq \psi(\mathbf{Y}_1[1], \dots, \mathbf{Y}_B[N], \mathbb{H}_1, \dots, \mathbb{H}_B). \quad (8)$$

The probability of error is defined as

$$P_e^{(\text{NB})} = \Pr[\hat{M} \neq M], \quad (9)$$

and the communication rate is given as

$$R = \frac{\log_2 M}{NB}. \quad (10)$$

A rate R is said to be achievable if there exists a sequence of codes such that $P_e^{(\text{NB})} \rightarrow 0$ as $B \rightarrow \infty$ (N remains fixed). The ergodic capacity $C_{\mathbb{H}}$ of the channel is defined as the supremum of all achievable rates.

III. NO CSI AT THE TRANSMITTER

In this section we assume that the transmitter has no CSI.¹ In this case, the channel input $\mathbf{X}_t[n]$ is just a function of the message M :

$$\mathbf{X}_t[n] = \phi_t(M), \quad (11)$$

¹Note that the channel *statistics* are always assumed to be known everywhere.

and the ergodic capacity is given by the following proposition.

Proposition 1: If the transmitter has no CSI, then

$$C_{\mathbb{H}} = \max_{P_{\mathbf{X}} \text{ satisfying (6)}} \mathbb{E}_{\mathbb{H}}[I(\mathbf{X}; \bar{\mathbf{X}} + \mathbf{Z} | \mathbb{H} = \mathbf{H})], \quad (12)$$

where

$$\bar{\mathbf{X}} \triangleq \mathbb{H}\mathbf{X}. \quad (13)$$

To obtain a lower bound on $C_{\mathbb{H}}$, we lower-bound the mutual information $I(\mathbf{X}; \mathbf{Y} | \mathbb{H} = \mathbf{H})$ for a given channel realization \mathbf{H} by using the independence between \mathbb{H} and \mathbf{Z} and invoking the EPI:

$$I(\mathbf{X}; \mathbb{H}\mathbf{X} + \mathbf{Z} | \mathbb{H} = \mathbf{H}) = h(\mathbb{H}\mathbf{X} + \mathbf{Z} | \mathbb{H} = \mathbf{H}) - h(\mathbf{Z}) \quad (14)$$

$$\geq \frac{1}{2} \log_2 \left(e^{2h(\mathbb{H}\mathbf{X} | \mathbb{H} = \mathbf{H})} + e^{2h(\mathbf{Z})} \right) - h(\mathbf{Z}) \quad (15)$$

$$= \frac{1}{2} \log_2 \left(1 + \frac{e^{2h(\mathbb{H}\mathbf{X} | \mathbb{H} = \mathbf{H})}}{(2\pi e)^{n_R}} \right) \quad (16)$$

$$= \frac{1}{2} \log_2 \left(1 + \frac{e^{2h(\mathbf{H}\mathbf{X})}}{(2\pi e)^{n_R}} \right), \quad (17)$$

where the last equality holds because without CSI at the transmitter, the input vector \mathbf{X} is independent of the channel matrix \mathbb{H} .

We now present choices of the distribution $P_{\mathbf{X}}$. Fix some $\lambda \in (0, \frac{n_R}{2})$ and let the n_R -dimensional random vector \mathbf{V} be exponentially distributed with density

$$f(\mathbf{v}) = \frac{1}{A^{n_R}} \left(\frac{\mu}{1 - e^{-\mu}} \right)^{n_R} e^{-\frac{\mu \|\mathbf{v}\|_1}{\lambda}}, \quad \mathbf{v} \in [0, A]^{n_R}, \quad (18)$$

where μ denotes the unique solution to

$$\frac{1}{\mu} - \frac{e^{-\mu}}{1 - e^{-\mu}} = \frac{\lambda}{n_R}. \quad (19)$$

Choose then some matrix \mathbf{G} with nonnegative entries, with $\text{rank}(\mathbf{G}) = n_R$, with $\|\mathbf{G}\|_1 \leq \alpha/\lambda$, and with row vectors satisfying $\|\mathbf{g}_i\|_1 \leq 1, \forall i \in \{1, \dots, n_T\}$, and define $P_{\mathbf{X}}$ as the distribution of the vector

$$\mathbf{X} = \mathbf{G}\mathbf{V}. \quad (20)$$

It can be verified that this choice of $P_{\mathbf{X}}$ satisfies the power constraints (6) and puts nonzero density only on nonnegative inputs.

Evaluating the lower bound in (17) for the proposed $P_{\mathbf{X}}$ and averaging over the channel matrix \mathbb{H} , yields the following result.

Theorem 2: If the transmitter has no CSI, then

$$C_{\mathbb{H}} \geq \frac{1}{2} \sup_{\lambda \in (0, \frac{n_R}{2})} \sup_{\mathbf{G}} \mathbb{E}_{\mathbb{H}} \left[\log_2 \left(1 + \frac{A^{2n_R} (\det \mathbb{H} \mathbf{G})^2 e^{2\nu}}{(2\pi e)^{n_R}} \right) \right]. \quad (21)$$

Here, the supremum is over all $n_T \times n_R$ matrices \mathbf{G} with nonnegative entries, with $\text{rank}(\mathbf{G}) = n_R$, with $\|\mathbf{G}\|_1 \leq \alpha/\lambda$,

and with row vectors satisfying $\|\mathbf{g}_i\|_1 \leq 1, \forall i \in \{1, \dots, n_T\}$; and ν is defined as

$$\nu \triangleq n_R \left(1 - \log_2 \frac{\mu}{1 - e^{-\mu}} - \frac{\mu e^{-\mu}}{1 - e^{-\mu}} \right) \quad (22)$$

with μ being the unique solution to (19).

Proof: We use the choice of $P_{\mathbf{X}}$ specified before Theorem 2. For a given realization of the channel matrix $\mathbb{H} = \mathbf{H}$, it implies the following density on the channel image vector $\bar{\mathbf{X}} = \mathbf{H}\mathbf{X}$:

$$f_{\mathbf{H}\mathbf{X}}(\bar{\mathbf{x}}) = \frac{1}{A^{n_R} |\det \mathbf{H}\mathbf{G}|} \cdot \left(\frac{\mu}{1 - e^{-\mu}} \right)^{n_R} e^{-\frac{\mu \|\mathbf{H}\mathbf{G}\|^{-1} \bar{\mathbf{x}}\|_1}{\lambda}}. \quad (23)$$

The differential entropy $h(\mathbf{H}\mathbf{X})$ thus evaluates to:

$$h(\mathbf{H}\mathbf{X}) = n_R \log_2(A \cdot |\det \mathbf{H}\mathbf{G}|) + n_R \left(1 - \log_2 \frac{\mu}{1 - e^{-\mu}} - \frac{\mu e^{-\mu}}{1 - e^{-\mu}} \right). \quad (24)$$

Combining this with (17), taking expectation over \mathbb{H} , and maximizing over the free parameters concludes the proof. ■

IV. PERFECT CSI AT TRANSMITTER

In this section, we assume that the transmitter has perfect CSI, i.e., the channel input $\mathbf{X}_t[n]$ is a function of the message M and the channel matrix \mathbb{H}_t :²

$$\mathbf{X}_t[n] = \phi_t(M, \mathbb{H}_t). \quad (25)$$

The ergodic capacity in this scenario is characterized as follows.

Proposition 3: If the transmitter has perfect CSI, then

$$C_{\mathbb{H}} = \mathbb{E}_{\mathbb{H}} \left[\max_{P_{\mathbf{X}|\mathbb{H}=\mathbf{H}} \text{ satisfying (6)}} I(\mathbf{X}; \bar{\mathbf{X}} + \mathbf{Z}|\mathbb{H} = \mathbf{H}) \right]. \quad (26)$$

As before, we present a choice of the input distribution $P_{\mathbf{X}|\mathbb{H}=\mathbf{H}}$ and evaluate the lower bound on capacity obtained with this distribution and the EPI. Our choice of $P_{\mathbf{X}|\mathbb{H}=\mathbf{H}}$ is based on the minimum-energy signaling strategy proposed in [9], [13], which we recall in the following.

A. Minimum-Energy Signaling

We notice that for a fixed channel matrix \mathbf{H} , when there are more transmit than receive antennas, i.e., $n_T > n_R$, then for certain image vectors $\bar{\mathbf{x}}$ there are different input vectors \mathbf{x} inducing $\bar{\mathbf{x}}$, i.e., satisfying $\mathbf{H}\mathbf{x} = \bar{\mathbf{x}}$. In [9], [13], an algorithm is presented which for each $\bar{\mathbf{x}}$ characterizes the vector \mathbf{x} that has minimum energy $\|\mathbf{x}\|_1$ among all input vectors inducing $\bar{\mathbf{x}}$.

Fix an $n_R \times n_T$ channel matrix \mathbf{H} for which every tuple of n_R columns is linearly independent. (The probability of the random channel matrix \mathbb{H} not being of this kind is 0 for any continuous and bounded density $f(\mathbb{H})$.) Note that since the

²More generally, one could allow the channel input $\mathbf{X}_t[n]$ to depend on all previous channel matrices $\mathbb{H}_1, \dots, \mathbb{H}_t$. But since we do not allow for power allocation across blocks and since the channel matrices are independent across blocks, the more general definition is not helpful.

input vector $\mathbf{x} \in [0, A]^{n_T}$, the image vector $\bar{\mathbf{x}} = \mathbf{H}\mathbf{x}$ takes value in the zonotope

$$\mathcal{R}(\mathbf{H}) \triangleq \{\bar{\mathbf{x}} : \bar{\mathbf{x}} = \mathbf{H}\mathbf{x}, \forall \mathbf{x} \in [0, A]^{n_T}\}. \quad (27)$$

Figure 1 shows the zonotope $\mathcal{R}(\mathbf{H})$ for two different 2×4 channel matrices \mathbf{H} .

We need some notation to describe the minimum-energy signaling in Lemma 4 ahead. Let \mathcal{U} be the set

$$\mathcal{U} \triangleq \{\mathcal{I} \subseteq \{1, 2, \dots, n_T\} : |\mathcal{I}| = n_R\}, \quad (28)$$

and for each $\mathcal{I} \in \mathcal{U}$, define

- the complement

$$\mathcal{I}^c \triangleq \{1, \dots, n_T\} \setminus \mathcal{I}; \quad (29)$$

- the n_R -dimensional parallelepiped

$$\mathcal{D}_{\mathcal{I}} \triangleq \left\{ \sum_{i \in \mathcal{I}} \lambda_i \mathbf{h}_i : \lambda_i \in [0, A], \forall i \in \mathcal{I} \right\}; \quad (30)$$

- the $n_R \times n_R$ submatrix

$$\mathbf{H}_{\mathcal{I}} \triangleq [\mathbf{h}_i : i \in \mathcal{I}]; \quad (31)$$

- the nonnegative number

$$s_{\mathcal{I}} \triangleq \sum_{j \in \mathcal{I}^c} \mathbb{1}\{\mathbf{1}_{n_R}^T \mathbf{H}_{\mathcal{I}}^{-1} \mathbf{h}_j > 1\}, \quad \mathcal{I} \in \mathcal{U}, \quad (32)$$

where $\mathbb{1}\{\cdot\}$ denotes the indicator function; and

- the n_R -dimensional vector

$$\mathbf{v}_{\mathcal{I}} \triangleq A \sum_{j \in \mathcal{I}^c} \mathbb{1}\{\mathbf{1}_{n_R}^T \mathbf{H}_{\mathcal{I}}^{-1} \mathbf{h}_j > 1\} \mathbf{h}_j. \quad (33)$$

Lemma 4 ([9], [13]): Given an $n_R \times n_T$ channel matrix \mathbf{H} , the following holds:

- 1) The zonotope $\mathcal{R}(\mathbf{H})$ is covered by the parallelepipeds $\{\mathbf{v}_{\mathcal{I}} + \mathcal{D}_{\mathcal{I}}\}_{\mathcal{I} \in \mathcal{U}}$, which overlap only on sets of measure zero.
- 2) For any $\mathcal{I} \in \mathcal{U}$ and $\bar{\mathbf{x}} \in (\mathbf{v}_{\mathcal{I}} + \mathcal{D}_{\mathcal{I}})$, the vector $\mathbf{x} = (x_1, \dots, x_{n_T})^T$ that induces $\bar{\mathbf{x}}$ with minimum energy is:

$$x_i = \begin{cases} a_{\mathcal{I},i}(\mathbf{H}) & \text{if } i \in \mathcal{I}^c, \\ \beta_{\mathcal{I},i}(\mathbf{H}, \bar{\mathbf{x}}) & \text{if } i \in \mathcal{I}, \end{cases} \quad (34)$$

where

$$a_{\mathcal{I},i}(\mathbf{H}) \triangleq A \cdot \mathbb{1}\{\mathbf{1}_{n_R}^T \mathbf{H}_{\mathcal{I}}^{-1} \mathbf{h}_j > 1\}, \quad i \in \mathcal{I}^c, \quad (35)$$

and the vector

$$\beta_{\mathcal{I}}(\mathbf{H}, \bar{\mathbf{x}}) = (\beta_{\mathcal{I},i}(\mathbf{H}, \bar{\mathbf{x}}) : i \in \mathcal{I})^T \quad (36a)$$

is given by

$$\beta_{\mathcal{I}}(\mathbf{H}, \bar{\mathbf{x}}) \triangleq \mathbf{H}_{\mathcal{I}}^{-1}(\bar{\mathbf{x}} - \mathbf{v}_{\mathcal{I}}). \quad (36b)$$

Figure 1 shows the partition of $\mathcal{R}(\mathbf{H})$ into 6 parallelepipeds for two 2×4 examples.

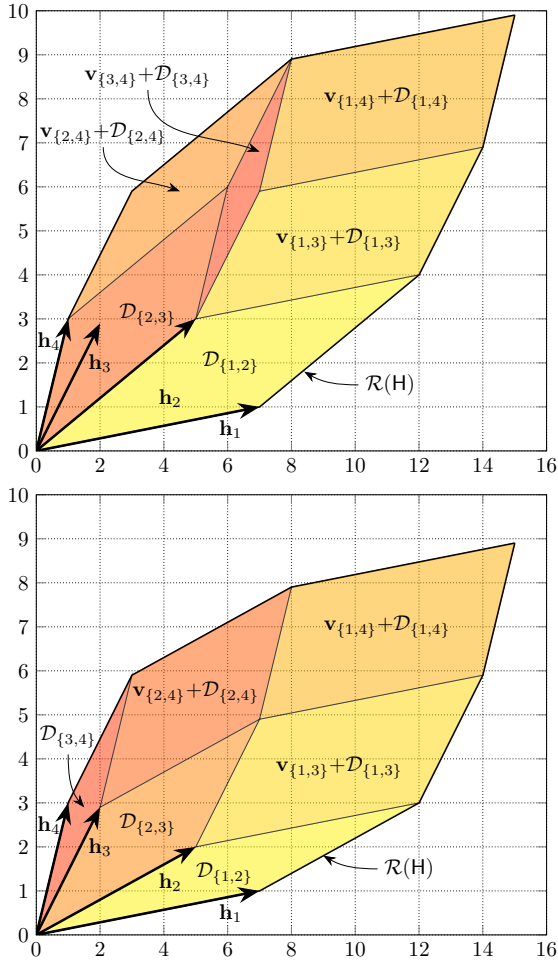


Fig. 1. Partition of $\mathcal{R}(\mathbf{H})$ into 6 parallelepipeds for two 2×4 MIMO examples. The example on the top is for $\mathbf{H} = [7, 5, 2, 1; 1, 2, 2.9, 3]$ and the example on the bottom for $\mathbf{H} = [7, 5, 2, 1; 1, 3, 2.9, 3]$.

B. The Choice of $P_{\mathbf{X}|\mathbb{H}=\mathbf{H}}$

Fix an $n_R \times n_T$ channel matrix \mathbf{H} for which every tuple of n_R columns is linearly independent.

The following parameters are important in this section. Let \mathbf{q} be a probability vector on \mathcal{U} with entries

$$q_{\mathcal{I}} \triangleq \frac{|\det \mathbf{H}_{\mathcal{I}}|}{\sum_{\mathcal{I}' \in \mathcal{U}} |\det \mathbf{H}_{\mathcal{I}'}|}, \quad \mathcal{I} \in \mathcal{U}, \quad (37)$$

and define

$$\alpha_{\text{th}}(\mathbf{H}) \triangleq \frac{n_R}{2} + \sum_{\mathcal{I} \in \mathcal{U}} s_{\mathcal{I}} q_{\mathcal{I}}. \quad (38)$$

If $\alpha \geq \alpha_{\text{th}}(\mathbf{H})$, we choose $P_{\mathbf{X}}$ so that $\bar{\mathbf{X}}$ is uniform over $\mathcal{R}(\mathbf{H})$. This is obtained by defining a random variable over \mathcal{U} with probability mass function (PMF) \mathbf{q} and conditional on $\tilde{U} = \mathcal{I}$, choose $\bar{\mathbf{X}}$ according to the minimum-energy signaling in (34) and so that $\bar{\mathbf{X}}$ is uniform over the shifted parallelepiped $\mathbf{v}_{\mathcal{I}} + \mathcal{D}_{\mathcal{I}}$.

If $\alpha < \alpha_{\text{th}}(\mathbf{H})$, we fix a parameter

$$\lambda \in \left(\max \left\{ 0, \frac{n_R}{2} + \alpha - \alpha_{\text{th}}(\mathbf{H}) \right\}, \min \left\{ \frac{n_R}{2}, \alpha \right\} \right) \quad (39)$$

and a PMF $\mathbf{p} = (p_{\mathcal{I}} : \mathcal{I} \in \mathcal{U})$ over the set \mathcal{U} so that

$$\sum_{\mathcal{I} \in \mathcal{U}} p_{\mathcal{I}} s_{\mathcal{I}} = \alpha - \lambda. \quad (40)$$

Let then \tilde{U} be a random variable over \mathcal{U} with PMF \mathbf{p} , and conditional on $\tilde{U} = \mathcal{I}$, choose $\bar{\mathbf{X}}$ according to the minimum-energy signaling in (34) and so that $\bar{\mathbf{X}}$ follows an n_R -dimensional truncated exponential distribution over the shifted parallelepiped $\mathbf{v}_{\mathcal{I}} + \mathcal{D}_{\mathcal{I}}$. Specifically, given $\mathbb{H} = \mathbf{H}$ and $\tilde{U} = \mathcal{I}$, the inputs $\{X_i : i \in \mathcal{I}^c\}$ are deterministically set to

$$X_i = a_{\mathcal{I},i}(\mathbf{H}), \quad i \in \mathcal{I}^c, \quad (41)$$

where $a_{\mathcal{I},i}(\mathbf{H})$ is defined in (35), and the remaining inputs $\{X_i : i \in \mathcal{I}\}$ are chosen as the truncated exponential distribution,

$$f_{X_i|\tilde{U}=\mathcal{I}}(x_i) = \frac{\mu}{1 - e^{-\mu}} e^{-\frac{\mu x_i}{\lambda}}, \quad \forall i \in \mathcal{I}. \quad (42)$$

Then at the receiver side, the image vector $\bar{\mathbf{X}} = \mathbf{H}\mathbf{X}$ is of conditional density

$$f_{\bar{\mathbf{X}}|\tilde{U}=\mathcal{I}}(\bar{\mathbf{x}}) = \frac{1}{A^{n_R} |\det \mathbf{H}_{\mathcal{I}}|} \cdot \left(\frac{\mu}{1 - e^{-\mu}} \right)^{n_R} e^{-\frac{\mu \|\mathbf{H}_{\mathcal{I}}^{-1}(\bar{\mathbf{x}} - \mathbf{v}_{\mathcal{I}})\|_1}{\lambda}}. \quad (43)$$

C. Capacity Lower Bound

Theorem 5: If the transmitter has perfect CSI, then

$$C_{\mathbb{H}} \geq \frac{1}{2} \mathbb{E}_{\mathbb{H}} \left[\log_2 \left(1 + \frac{A^{2n_R} V_{\mathbb{H}}^2}{(2\pi e)^{n_R}} e^{2\nu(\mathbb{H})} \right) \right], \quad (44)$$

where for each realization of the channel matrix \mathbf{H} :

$$V_{\mathbf{H}} \triangleq \sum_{\mathcal{I} \in \mathcal{U}} |\det \mathbf{H}_{\mathcal{I}}|, \quad (45)$$

and if $\alpha \geq \alpha_{\text{th}}(\mathbf{H})$, then

$$\nu(\mathbf{H}) \triangleq 0, \quad (46)$$

whereas if $\alpha < \alpha_{\text{th}}(\mathbf{H})$, then

$$\nu(\mathbf{H}) \triangleq \left. \begin{aligned} & \sup_{\lambda \in (\max\{0, \frac{n_R}{2} + \alpha - \alpha_{\text{th}}\}, \min\{\frac{n_R}{2}, \alpha\})} \left\{ \right. \\ & \left. n_R \left(1 - \log_2 \frac{\mu}{1 - e^{-\mu}} - \frac{\mu e^{-\mu}}{1 - e^{-\mu}} \right) - \inf_{\mathbf{p}} \mathbb{D}(\mathbf{p} \parallel \mathbf{q}) \right\}. \end{aligned} \right\} \quad (47)$$

Thus, $\nu(\mathbf{H})$ is nonpositive and corresponds to the penalty due to α .

Proof: Consider first the case $\alpha \geq \alpha_{\text{th}}(\mathbf{H})$. With the proposed choice ($\bar{\mathbf{X}}$ uniform over $\mathcal{R}(\mathbf{H})$), for each realization $\mathbb{H} = \mathbf{H}$, the conditional differential entropy is

$$h(\bar{\mathbf{X}}|\mathbb{H} = \mathbf{H}) = \log_2(A^{n_R} \cdot V_{\mathbf{H}}). \quad (48)$$

Combining this with (16) yields the desired result.

Consider now the case $\alpha < \alpha_{\text{th}}(\mathbf{H})$. We define U to be a discrete random variable that is obtained by applying a function on $\bar{\mathbf{X}}$ in a way to satisfy:

$$(U = \mathcal{I}) \iff (\bar{\mathbf{X}} \in (\mathbf{v}_{\mathcal{I}} + \mathcal{D}_{\mathcal{I}})). \quad (49)$$

We then start from (16) and decompose the conditional differential entropy $h(\bar{\mathbf{X}}|\mathbb{H} = \mathbf{H})$ as

$$\begin{aligned} h(\bar{\mathbf{X}}|\mathbb{H} = \mathbf{H}) &= I(\bar{\mathbf{X}}; U|\mathbb{H} = \mathbf{H}) + h(\bar{\mathbf{X}}|U, \mathbb{H} = \mathbf{H}) \quad (50) \\ &= H(U|\mathbb{H} = \mathbf{H}) + h(\bar{\mathbf{X}}|U, \mathbb{H} = \mathbf{H}) \quad (51) \end{aligned}$$

where we used that U is a function of $\bar{\mathbf{X}}$. Notice that we do not specify the value of U when $\bar{\mathbf{X}}$ lies on the border of a parallelepiped $\mathbf{v}_{\mathcal{I}} + \mathcal{D}_{\mathcal{I}}$. However, the way we picked $\bar{\mathbf{X}}$ this event happens with probability 0 and does not influence the entropies. Moreover, with probability 1, $U = \tilde{U}$ and these two random variables thus have same (conditional) entropies. By the choice of the PMF \mathbf{p} in (40) and the exponential distribution in (43), we then have:

$$h(\bar{\mathbf{X}}|\mathbb{H} = \mathbf{H}) = H(\tilde{U}|\mathbb{H} = \mathbf{H}) + h(\bar{\mathbf{X}}|\tilde{U}, \mathbb{H} = \mathbf{H}) \quad (52)$$

$$\begin{aligned} &= H(\mathbf{p}) + \log_2 |\det \mathbf{H}_{\mathcal{I}}| + n_{\mathbf{R}} \log_2 A \\ &\quad + n_{\mathbf{R}} \left(1 - \log_2 \frac{\mu}{1 - e^{-\mu}} - \frac{\mu e^{-\mu}}{1 - e^{-\mu}} \right) \quad (53) \end{aligned}$$

$$\begin{aligned} &= -D(\mathbf{p}||\mathbf{q}) + \log_2 V_{\mathbf{H}} + n_{\mathbf{R}} \log_2 A \\ &\quad + n_{\mathbf{R}} \left(1 - \log_2 \frac{\mu}{1 - e^{-\mu}} - \frac{\mu e^{-\mu}}{1 - e^{-\mu}} \right). \quad (54) \end{aligned}$$

The result now follows from substituting (54) into (16), and then maximizing over the free parameters λ and \mathbf{p} .

Finally, we take expectation over \mathbb{H} . \blacksquare

Next, we present an upper bound on capacity.

Theorem 6: If the transmitter has perfect CSI, then

$$C_{\mathbb{H}} \leq \mathbb{E}_{\mathbb{H}} \left[C_{\mathbb{H},1} \mathbb{1}\{\alpha \geq \alpha_{\text{th}}(\mathbb{H})\} + C_{\mathbb{H},2} \mathbb{1}\{\alpha < \alpha_{\text{th}}(\mathbb{H})\} \right], \quad (55)$$

where for each realization of the channel matrix \mathbf{H} :

$$C_{\mathbb{H},1} \triangleq n_{\mathbf{R}} \log_2 \left(\sigma_{\max} + \frac{A}{\sqrt{2\pi e}} \right) + \log_2 V_{\mathbf{H}}, \quad (56)$$

and

$$\begin{aligned} C_{\mathbb{H},2} \triangleq \sup_{\mathbf{p}} \inf_{\mu > 0} \left\{ n_{\mathbf{R}} \log_2 \left(\sigma_{\max} + \frac{A}{\sqrt{2\pi e}} \frac{1 - e^{-\mu}}{\mu} \right) \right. \\ \left. + \log_2 V_{\mathbf{H}} + \frac{\mu n_{\mathbf{R}} \sigma_{\max}}{A \sqrt{2\pi}} \left(1 - e^{-\frac{\Lambda^2}{2\sigma_{\min}}} \right) \right. \\ \left. + \mu \left(\alpha - \sum_{\mathcal{I} \in \mathcal{U}} p_{\mathcal{I}} s_{\mathcal{I}} \right) - D(\mathbf{p}||\mathbf{q}) \right\} \quad (57) \end{aligned}$$

with the supremum being over all \mathbf{p} on \mathcal{U} and with

$$\sigma_{\max} \triangleq \max_{\mathcal{I} \in \mathcal{U}} \sigma_{\mathcal{I},\ell} \quad \text{and} \quad \sigma_{\min} \triangleq \min_{\mathcal{I} \in \mathcal{U}} \sigma_{\mathcal{I},\ell}, \quad (58)$$

$\ell \in \{1, \dots, n_{\mathbf{R}}\}$ $\ell \in \{1, \dots, n_{\mathbf{R}}\}$

where $\sigma_{\mathcal{I},\ell}$ denotes the square root of the ℓ th diagonal entry of the matrix $\mathbf{H}_{\mathcal{I}}^{-1} \mathbf{H}_{\mathcal{I}}^{-\top}$.

Finally, we analyze the asymptotic capacity for $A, E \rightarrow \infty$ with α held fixed.

Theorem 7: If the transmitter has perfect CSI, then

$$\begin{aligned} &\lim_{A \rightarrow \infty} \{ C_{\mathbb{H}} - n_{\mathbf{R}} \log_2 A \} \\ &= \frac{1}{2} \mathbb{E}_{\mathbb{H}} \left[\log_2 \left(\frac{V_{\mathbb{H}}^2}{(2\pi e)^{n_{\mathbf{R}}}} \right) + \nu(\mathbb{H}) \mathbb{1}\{\alpha < \alpha_{\text{th}}(\mathbb{H})\} \right], \quad (59) \end{aligned}$$

where for each realization of the channel matrix \mathbf{H} , $\nu(\mathbf{H})$ is defined by (46) for $\alpha \geq \alpha_{\text{th}}(\mathbf{H})$ and by (47) for $\alpha < \alpha_{\text{th}}(\mathbf{H})$.

V. LIMITED CSI AT TRANSMITTER

In this section we assume an instantaneous rate-limited *channel state feedback link* from the receiver to the transmitter. At the very beginning of each block, before transmission begins, the receiver learns \mathbb{H}_t and sends a function of it,

$$\mathcal{F}_t(\mathbb{H}_t), \quad (60)$$

back to the transmitter.

The transmitter can thus compute its channel inputs $\mathbf{X}_t[n]$ as a function of the received feedback $\mathcal{F}_t(\mathbb{H}_t)$ and the message M :

$$\mathbf{X}_t[n] = \phi(\mathcal{F}_t(\mathbb{H}_t), M). \quad (61)$$

Of course, the capacity of this channel depends on the functions $\{\mathcal{F}_t\}_{t=1}^B$. We will assume a *stationary* feedback policy where

$$\mathcal{F}_1 = \dots = \mathcal{F}_B = \mathcal{F}. \quad (62)$$

Proposition 8: The capacity $C_{\mathbb{H},\mathcal{F}}$ of a channel with limited CSI $\mathcal{F}(\mathbb{H})$ at the transmitter is:

$$C_{\mathbb{H},\mathcal{F}} = \mathbb{E}_{\mathbb{H}} \left[\max_{P_{\mathbf{X}|\mathcal{F}(\mathbf{H})} \text{ satisfying (6)}} I(\mathbf{X}; \mathbf{Y}|\mathbb{H} = \mathbf{H}) \right]. \quad (63)$$

We present a choice of the function \mathcal{F} with only $\binom{n_{\mathbf{T}}}{n_{\mathbf{R}}}$ function values, for which the corresponding capacity with limited CSI is close to the one with perfect CSI. Obviously, to implement this function it suffices that the receiver can feed back

$$R_{\text{FB}} = (n_{\mathbf{T}} - n_{\mathbf{R}}) \log_2 \binom{n_{\mathbf{T}}}{n_{\mathbf{R}}} \quad (64)$$

bits in each block.

Before describing our choice of \mathcal{F} , we notice that to achieve the rates in Theorem 5, it suffices that the transmitter learns the binary values $\{a_{\mathcal{I},i}(\mathbf{H})\}_{\mathcal{I} \in \mathcal{U}}$ and the PMF \mathbf{p} for each realization of \mathbf{H} . Learning the PMF \mathbf{p} at the transmitter requires the state-feedback to have infinite number of bits. In contrast, the binary values $\{a_{\mathcal{I},i}(\mathbf{H})\}_{\mathcal{I} \in \mathcal{U}}$ can be learned with only $(n_{\mathbf{T}} - n_{\mathbf{R}}) \log_2 \binom{n_{\mathbf{T}}}{n_{\mathbf{R}}}$ bits of feedback.

We thus propose to set

$$\mathcal{F}(\mathbf{H}) \triangleq (a_{\mathcal{I},i}(\mathbf{H}) : \mathcal{I} \in \mathcal{U}, i \in \mathcal{I}^c). \quad (65)$$

The transmitter then uses the following conditional distribution $P_{\mathbf{X}|\mathcal{F}}$ to generate its (random) codebook for transmitting the desired message M . For each realization $\mathcal{F} = \mathbf{f}$, pick an arbitrary positive number $\lambda \in (0, \frac{n_{\mathbf{R}}}{2})$ and let μ denote the solution to (19) for the picked value of λ . Then for this λ , pick an arbitrary PMF \mathbf{p} over \mathcal{U} satisfying (40), and let $\tilde{U} \sim \mathbf{p}$. (By (32), (35), and (65), the parameters $\{s_{\mathcal{I}}\}_{\mathcal{I} \in \mathcal{U}}$ in condition (40) depend on \mathbf{H} only through $\mathcal{F}(\mathbf{H})$, and thus the proposed \mathbf{p} can be used as a parameter for the distribution

$P_{\mathbf{X}|\mathcal{F}(\mathbb{H})}$.) Similarly to before, given that $\mathcal{F} = \mathbf{f}$ and $\tilde{\mathcal{U}} = \mathcal{I}$, we deterministically set

$$X_i = a_{\mathcal{I},i}(\mathbf{H}), \quad i \in \mathcal{I}^c, \quad (66)$$

and choose the remaining inputs $\{X_i : i \in \mathcal{I}\}$ according to the distribution in (42).

Theorem 9: For the limited CSI function \mathcal{F} in (65):

$$\begin{aligned} & C_{\mathbb{H},\mathcal{F}} \\ & \geq \mathbf{E}_{\mathcal{F}(\mathbb{H})} \left[\sup_{\lambda \in (0, \frac{n_R}{2})} \sup_{\mathbf{p}} \mathbf{E}_{\mathbb{H}|\mathcal{F}} \left[\frac{1}{2} \log \left(1 + \frac{A^{2n_R} V_{\mathbb{H}}^2 e^{2\nu^*}}{(2\pi e)^{n_R}} \right) \right] \right] \end{aligned} \quad (67)$$

where

$$\nu^* \triangleq n_R \left(1 - \log_2 \frac{\mu}{1 - e^{-\mu}} - \frac{\mu e^{-\mu}}{1 - e^{-\mu}} \right) - D(\mathbf{p}||\mathbf{q}), \quad (68)$$

with μ satisfying (19), and where the supremum over \mathbf{p} is over all PMFs satisfying (40).

Proof: The proof is similar to the proof of Theorem 5 except that now the choices of λ and \mathbf{p} can depend on \mathbb{H} only through $\mathcal{F}(\mathbb{H})$. The details are omitted. ■

VI. NUMERICAL EXAMPLE

Figure 2 illustrates the derived upper and lower bounds on the capacities for a 1×3 MISO channel where the entries $\{h_i\}_{i \in \{1,2,3\}}$ in the channel matrix \mathbb{H} are IID and follow a Rayleigh distribution:

$$f(h_i) = 2h_i e^{-h_i^2} \mathbb{1}\{h_i \geq 0\}, \quad \forall i \in \{1, 2, 3\}. \quad (69)$$

When the SNR tends to infinity, the lower bound in Theorem 5 coincides with the upper bound in Theorem 6. Furthermore, the gap between the lower bound in Theorem 9 below and the upper bound in Theorem 6 tends to a small constant at high SNR. Thus, at high SNR a relatively small number of feedback bits is sufficient to approach the perfect CSI capacity.

VII. CONCLUSION

In this paper we derived lower bounds on the capacity of block fading channels in the three cases where the transmitter has no CSI, perfect CSI, and limited CSI, respectively. For perfect and limited CSI, our lower bounds are based on the minimum-energy signaling strategy in [9]. In particular, for limited CSI, in each block, the receiver feeds back only the binary values $\{a_{\mathcal{I},i}(\mathbf{H})\}_{\mathcal{I} \in \mathcal{U}}$ where \mathbf{H} denotes the channel realization in this block. This requires only $(n_T - n_R) \log_2 \binom{n_T}{n_R}$ bits of feedback per block, but the corresponding lower bound performs close to the lower bound with perfect CSI.

In the case of perfect CSI we also provided an upper bound on capacity and showed that it approaches the proposed lower bound asymptotically in the high-SNR regime. In this regime, the perfect CSI capacity can thus be closely approached with only a small number of feedback bits per block.

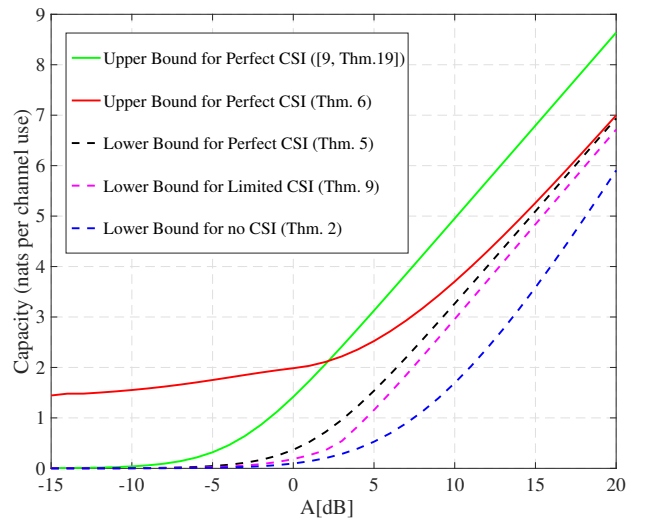


Fig. 2. A 1×3 MISO channel, where entries in $\mathbb{H}_{1 \times 3}$ follow a Rayleigh distribution, with $\alpha = 0.4$.

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